

Monitoring On-orbit radiometric stability of the L7 ETM+, Terra MODIS, & IRS-P6 AWiFS sensors using pseudoinvariant test sites

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U.S. Department of the Interior

U.S. Geological Survey

Outline

- Background
- RSR Comparison
- Methodology
- Cross-calibration Results
- Summary



Need for cross-calibration

- The ability to detect and quantify changes in the Earth's environment depends on sensors that can provide calibrated, consistent measurements of the Earth's surface features through time
- A critical step in this process is to put image data from different sensors onto a common radiometric scale
- The cross-calibration techniques use a well-calibrated sensor as a form of transfer radiometer to achieve characterization of other sensors using near-simultaneous observations of the Earth
 - Cross-calibration is the only viable solution to tie similar sensors (TM) and differing sensors (TM-ETM+) onto a common radiometric scale, thus providing an important role in mission continuity, interoperability, and data fusion
 - Cross-calibration is useful in situations where on-board references are not available or where vicarious calibration is not feasible
 - Cross-calibration between sensors is critical to coordinate observations from different sensors, exploiting their individual spatial resolutions, temporal sampling, and information content to monitor surface processes over broad scales in both time and space



Multi-Sensor Solutions (MSS) Architecture

- Increasingly, data from multiple sensors are used to gain a more complete understanding of land surface processes at a variety of scales
- The success of MSS architecture depends on how well the contributed sensors achieve "Interoperability"
- Here, interoperability is that condition wherein differences among systems are not a barrier to a task that spans those sensors
- The focus is on how sensors work together
- The MSS architecture should provide the specifications of just those "few things that must be similar"
- Interoperability Arrangements "What few things must be the same so that everything else can be different?" Eliot Christian





Sensor Overview

Platform	Terra	Landsat 7	IRS-P6	
Sensor	MODIS	ETM+	AWiFS	
Number of bands	36	8	4	
Spatial resolution	patial resolution 250 m, 500 m, 1 km		56 m (near nadir), 70 m (near edge)	
Swath	2360 km	187 km	740 km	
Spectral coverage	0.4~14 μm	0.4~12.5 μm	0.52~1.7 μm	
Pixel quantization	Pixel quantization 12 bit		10 bit	
Launch date	Dec 18, 1999	Apr 15, 1999	Oct 17, 2003	
Orbit type	Sun synchronous	Sun synchronous	Sun synchronous	
Altitude	705 km	705 km	817 km	





Spectral Band Comparison





Figure of Merit (alpha)

- The Figure of Merit ("alpha") is defined as the intersecting areas of two spectral response functions divided by the union of the two areas
 - alpha = 1.0 indicates complete spectral agreement between two bands
 - alpha = 0.0 indicates complete disagreement

$$\alpha = \frac{A \cap B}{A \cup B}$$





- The figure of merit approach is plagued by the lack of spectral scene content information, but at least provides a non-unity factor
 - For a spectrally flat scene, the RSR differences will not matter
- The figure of merit can be viewed more as a quantization of 'potential' differences in cross-cal between the sensors



Spectral Band Comparison

	L7 ETM+		Terra MODIS			IRS-P6 AWIFS		
Band	(μm)	Res.(m)	Band	(µm)	Res.(m)	Band	(µm)	Res.(m)
1	0.450 - 0.515	30	3	0.459-0.479	500			
2	0.525 - 0.605	30	4	0.545-0.565	500	2	0.520-0.590	56
3	0.630 - 0.690	30	1	0.62-0.67	250	3	0.620-0.680	56
4	0.775 - 0.900	30	2	0.841-0.876	250	4	0.770-0.860	56
5	1.550 - 1.750	30	6	1.628-1.652	500	5	1.550-1.700	56
7	2.090 - 2.350	30	7	2.105-2.155	500			

Figure of Merit

Figure of Merit (alpha)						
P6 AWIFS FOM comparison						
Bands	ETM+	TM	MODIS			
2	0.819	0.674	0.285			
3	0.608	0.620	0.655			
4	0.543	0.504	0.136			
5	0.687	0.556	0.233			



Catalog of World-wide Test Sites http://calval.cr.usgs.gov/





Radiometry Sites







Online Catalogue Example: Railroad Valley Playa, North America

Radiometric	Prev Next	Choose A Geometry Ste 🕑	19 May 2003
Location (City, State, Country):	Ely, Neveda, USA, North America	nems Test Ste Gallery	nder Sites
Altitude above sea level (meters):	1435	Subaraha Sina	
Center Latitude Longitude (Degrees):	438.5 -115.69	ALCONT ON A DESCRIPTION OF A DESCRIPTION	
Lendest WRS-2 Peth/Row:	40 / 33	Geometry Sites	
Size of Useble Ares (km):	10 × 10	Among and a second s	
Owner:	Surceu of Land Management (SLM)	Roferences ETH+ Bends 321 Zoomed	ETM+ Sende 321 Site Persmeters
Researcher:	Dr. Kurba J. Thome Emeil Researcher	19-May/2003	No. of Concession, Name
	Site Location	87M+ Bande 321	Google Earth Zoomed
AN -	Described LT STALL GesTM		
lan Antoni Prina	2a		
Purpose: Rediometric, vicerious celibrat	Ion test site with large homogenous		
regiona		Ground Picture 1	Ground Picture 2
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Test Sites Gallery





Test Sites (Libya 4 & RVPN)

- Location (City, State, Country): Libya, Africa
- Altitude above sea level (meters): 118
- Center Latitude, Longitude (Degrees): +28.55, +23.39
- Landsat WRS-2 Path/Row: 181 / 40
- High reflectance in visible bands
- Large sand dunes with no vegetation
- Used extensively for long-term stability monitoring
- Location (City, State, Country): Ely, Nevada, USA
- Altitude above sea level (meters): 1435
- Center Latitude, Longitude (Degrees): +38.5, -115.69
- Landsat WRS-2 Path/Row: 40 / 33
- Used extensively for field campaigns





ETM+ Bands: 321 Zoomed



Image Pairs Selection Criteria

- Near-simultaneous pairs (within 30 min)
- Repeat Cycle in days
 - ETM+ (16), MODIS (1) AWiFS (5)
- Cloud free
- ROI is close to nadir angle for MODIS & ETM+



AWiFS



Libya 4 Test Site

MODIS

ETM+



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ETM+ RVPN Test Site





Methodology

- Each sensor is well-characterized radiometrically & geometrically
- Co-located areas identified for each image pairs
- At-sensor radiance (W/m²/sr/µm) and at-sensor reflectance [0,1] were computed for all scenes
- Linear fits, average percent differences and RMSE's computed for each band

$$\rho_P = \frac{\Pi \bullet L_\lambda \bullet d^2}{ESUN_\lambda \bullet \cos \theta_s}$$

 $\begin{array}{l} \rho_{\text{P}} = \text{unitless planetary reflectance} \\ \mathsf{L}_{\lambda} = \text{spectral radiance at the sensor's aperture} \\ \mathsf{d} = \text{Earth-Sun distance in astronomical units} \\ \mathsf{ESUN}_{\lambda} = \text{Solar exoatmospheric mean irradiances} \\ \theta_{\text{s}} = \text{solar zenith angle in degrees} \end{array}$

Exoatmospheric Solar Spectral Irradiances							
	ESUN UNITS = W/m² μm						
ETM+ (ETM+ (CHKUR) MODIS (WRC) AWIFS (CHKUR)						
1	1969	3	2015.1				
2	1840	4	1859.1	2	1849.82		
3	1551	1	1606.1	3	1579.37		
4	1044	2	991.72	4	1075.11		
5	225.7	6	239.63	5	235.83		
7	82.07	7	89.385				





Results

- Scene standard deviation bars are added
- Linear equations are fitted
 - Slope values are very small
 - There are constant offsets
- The annual oscillation were caused by BRDF effect
- The slope values prove the long term stability of the two sensors
- The residue standard deviation values are within the 2% of radiometric specifications











Time Series: Libya 4





Time Series: RVPN





Time Series: RVPN







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Time Series: RVPN





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Comparison Table

USGS

MODIS					ETM+				
Band	Slope	Intercept	lmage STD	Residue STD	Band	Slope	Intercept	lmage STD	Residue STD
	Libya 4 Site								
1	-1.1E-6	0.43	0.018	0.007	3	8.3E-7	0.45	0.011	0.005
2	1.3E-7	0.56	0.019	0.011	4	8.8E-7	0.54	0.020	0.011
3	-3.1E-6	0.24	0.012	0.003	1	-2.8E-7	0.25	0.009	0.002
4	-7.5E-8	0.32	0.014	0.004	2	3.5E-7	0.34	0.010	0.003
6	-1.8E-7	0.69	0.019	0.013	5	4.2E-7	0.64	0.016	0.010
7	9.1E-7	0.62	0.031	0.020	7	1.4E-6	0.55	0.0302	0.016
RVPN Site									
1	-1.9E-6	0.35	0.065	0.023	3	-1.1E-6	0.36	0.057	0.020
2	-8.3E-7	0.4	0.063	0.025	4	-1.4E-6	0.40	0.057	0.022
3	-4.8E-6	0.28	0.061	0.017	1	-2.6E-6	0.29	0.058	0.016
4	-1.3E-6	0.32	0.065	0.021	2	-1.2E-6	0.32	0.059	0.019
6	-1.7E-6	0.43	0.070	0.028	5	-3.0E-6	0.41	0.061	0.024
7	-1.8E-6	0.36	0.1	0.034	7	-2.2E-6	0.32	0.087	0.027



Summary and Future Work

- A long-term radiometric stability evaluation between Terra MODIS and L7 ETM+ was performed using near-simultaneous scene pairs over the uniform Libyan 4 (56 image pairs) desert target and RVPN (78 image pairs) covering the lifetime of the two sensors
- ETM+ and MODIS sensors showed excellent long-term TOA reflectance stability generally within 2%
 - Results are consistent between Libya 4 and RVPN sites
- Results from AWiFS sensors show short term stability
 - Need to monitor the long term trends & absolute calibration
- ISRO should acquire and archive imagery over five top tier sites!
 - Get access to AWiFS data from NRSA & ASRC archive
- Additional work is underway to characterize the uncertainties due to spectral mismatches, spatial, BRDF, and atmospheric impacts



Backup Slides



CEOS IVOS-19 Test sites Discussion Summary

Invariant Sites							
#	Site Name	Center Latitude	Center Longitude				
1	Libya 4	28.55	23.39				
2	Mauritania 1	19.40	-9.30				
2	Mauritania 2	20.85	-8.78				
3	Algeria 3	30.32	7.66				
4	Libya 1	24.42	13.35				
5	Algeria 5	31.02	2.23				
Core Instrumented Sites							
1	Railroad Valley Playa	38.50	-115.69				
2	Ivanpah Playa	35.57	-115.40				
3	Lspec Frenchman Flat	36.81	-115.93				
4	La Crau	43.47	4.97				
5	Dunhuang	40.13	94.34				
6	Negev, Southern Israel	30.11	35.01				
7	Tuz Golu	38.83	33.33				
8	Dome C	-74.50	123.00				

Mauritania (consider as one site)



Core "Instrumented" IVOS Sites (Total=8) LANDNET

1. Railroad Valley Playa, NV, USA, North America

Dr. Kurtis J. Thome (<u>kthome@email.arizona.edu</u>) – University of Arizona, USA

2. Ivanpah, NV/CA, USA, North America

Dr. Kurtis J. Thome (<u>kthome@email.arizona.edu</u>) – University of Arizona, USA

3. Lspec Frenchman Flat, NV, USA, North America

Mark C. Helmlinger (<u>mark.helmlinger@ngc.com</u>) – NGST, USA

4. La Crau, France, Europe

Patrice Henry (<u>patrice.henry@cnes.fr</u>) – CNES, France

5. Dunhuang, Gobi Desert, Gansu Province, China, Asia

Fu Qiaoyan (fqy@cresda.com) – CRESDA, China

6. Negev, Southern Israel, Asia

– Arnon Karnieli (karnieli@bgu.ac.il) – Ben Gurion University, Israël

7. Tuz Golu, Central Anatolia, Turkey, Asia

Selime Gurol (<u>selime.gurol@uzay.tubitak.gov.tr</u>) – TUBITAK UZAY, Turkey

8. Dome C, Antartica

Dr. Stephen Warren (<u>sgw@atmos.washington.edu</u>) – University of Washington, USA



Core "Instrumented" IVOS Sites (Total=8)





"Invariant" IVOS Sites (Total=5)

- Libya 4
- Mauritania 1/2
- Algeria 3
- Libya 1
- Algeria 5







Spectral Band Comparison





Spectral Band Adjustment Factors (SBAF)



 $SBAF = \underbrace{\left(\int \rho(\lambda) \bullet Eo(\lambda) \bullet R(\lambda) \bullet d\lambda \right) \int Eo(\lambda) \bullet R(\lambda) \bullet d\lambda}_{\left(\int \rho(\lambda) \bullet Eo(\lambda) \bullet R(\lambda) \bullet d\lambda \right) \int Eo(\lambda) \bullet R(\lambda) \bullet d\lambda}$

Simulated ETM+ $\rho^*(\lambda)'_{ETM+} = SBAF \cdot \rho^*(\lambda)_{MODIS}$



SBAF: RVPN Site (Surface Reflectance)



2005-08-12 2004-12-15 2004-07-08 **2004-03-18** 2003-07-22 2002-06-17

RVPN Surface reflectance spectra were kindly provided by UoA RS Group



SBAF: Libya 4 Site (EO-1 Hyperion Data)



Libya 4



SBAF for RVPN Dataset

ETM+ B1 & MODIS B3 (RVPN)





SBAF for Libya 4 Dataset

ETM+ B1 & MODIS B3 (Libya 4)



No.